

Information and voting: Evidence from Peru's 2026 presidential election

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Preliminary draft. This paper is strictly theoretical and empirical, and does not reflect the political views or preferences of the authors.

Outline

- 1 Motivation and natural experiment
- 2 Model
- 3 Data and empirical strategy
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- 5 Conclusion

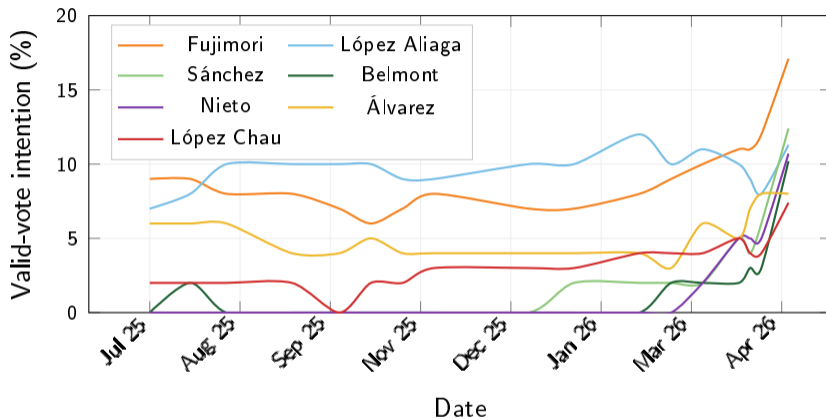
Motivation

- In multi-candidate plurality elections with weak party identification, late public signals about candidate **viability** can change voters' minds.
- Peru 2026: extraordinarily fragmented first round — **36 candidates**, weak party brands, a documented logic of rejection (*mal menor*) rather than affiliation.
- On election night the two leading pollsters released *flash electoral* estimates minutes apart:
 - Both agreed: **Fujimori** first.
 - They **disagreed** on second: Datum named **López Aliaga**; Ipsos named **Sánchez**; **Nieto** within the margin of error in both.

Question

What is the causal effect of election-night flash estimates on voting behavior?

Polling dynamics: a fragmented, late-deciding field



Ipsos Perú regular tracker, Jul 2025–Apr 2026 (valid-vote basis). Only Fujimori is clearly ahead at the close; Sánchez, Nieto, and Belmont surge in the final weeks — the second slot is undecided going into election night. Source: *La Encerrona* poll tracker.

The natural experiment

The logistical failure

- Sunday 12 April 2026: **187 polling tables** across **13 voting centers** (Lima Sur) failed to install — materials were not delivered on time.
- The *Jurado Nacional de Elecciones* (JNE) moved the affected $\approx 55\,000$ electors to **Monday 13 April**.

Treatment

- *Monday* voters cast ballots **after** the Ipsos and Datum flash estimates and the partial count.
- Comparable *Sunday* voters did not.

Identification

Assignment driven by a logistical failure, not by voter characteristics \Rightarrow compare treated vs. matched control *locales de votación*.

Election night: the flash estimates

- No clear front-runner: Fujimori 17.06%, Sánchez 12.04%, López Aliaga 11.90%, Nieto 11.03% — barely a point separating the second runoff slot.
- 18:00, 12 April — Ipsos and Datum release flash estimates:
 - Datum: López Aliaga second (12.8%). Ipsos: Sánchez second (12.1%), Belmont third (11.8%).
 - Nieto within a percentage point of the named candidates in both.
- The estimates **confirmed Fujimori's passage** and rendered **three candidates viable** for the remaining slot, spanning the spectrum:

López Aliaga

right

Nieto

center, off-axis

Sánchez

left

Contributions

- 1 **Empirical (central)**. Exploit the JNE ruling as a natural experiment; identify the causal effect of overnight flash estimates via **cardinality matching** at the polling-place level and a within-group regression estimator.
- 2 **New dataset**. *Locales de votación* characterized socioeconomically from block-level (*manzana*) INEI Redatam census data merged with ONPE *actas* for 2021 and 2026.
- 3 **Theory as organizing device**. Bayesian-updating / information-design model (Kamenica–Gentzkow; Blackwell): treatment is a Blackwell improvement of the public experiment, and an identification result equates the matching ATT with its behavioral value.

Model: states and signals

States. Fujimori's first place is uncontested; uncertainty is over the **identity of the runoff entrant**,

$$\Theta = \{\text{RS}, \text{RLA}, \text{JN}\}, \quad K \equiv |\Theta| = 3, \quad \mu \in \Delta(\Theta), \quad \mu_0 \text{ the common prior.}$$

Signals. Each pollster's flash is a symmetric η -noisy experiment with signal space $S = \Theta$ and error rate η :

$$\pi^\eta(s | \theta) = \begin{cases} 1 - \eta, & s = \theta, \\ \frac{\eta}{K - 1}, & s \neq \theta, \end{cases} \quad \eta \in \left[0, 1 - \frac{1}{K}\right).$$

- η absorbs sampling and non-sampling error and yields a clean Blackwell ordering: $\pi^{\eta_1} \succeq_B \pi^{\eta_2}$ iff $\eta_1 \leq \eta_2$.
- Voters observe **two** public signals (s_D, s_I) (Datum, Ipsos). In 2026 the calls were **discordant**, $s_D^* \neq s_I^*$.

Bayesian updating: one signal

A *signal* is a kernel $\pi : \Theta \rightarrow \Delta(S)$; the *posterior* $\mu(\theta | s^*)$ is the updated belief that the true state is θ after observing the call s^* . For a realized call $s^* \in \Theta$, Bayes' rule on the η -noisy kernel gives

$$\mu(\theta | s^*) = \begin{cases} \frac{(1 - \eta) \mu_0(s^*)}{Z}, & \theta = s^*, \\ \frac{(\eta/(K - 1)) \mu_0(\theta)}{Z}, & \theta \neq s^*, \end{cases} \quad Z = (1 - \eta) \mu_0(s^*) + \frac{\eta}{K-1} (1 - \mu_0(s^*)),$$

where Z is the normalizing constant (the marginal probability of the call s^*). A noisier flash (larger η) pulls the posterior back toward the prior μ_0 .

Bayesian updating: two signals and the 2026 posterior

With **two conditionally independent signals** (s_D^*, s_I^*) (Datum, Ipsos) of error rates (η_D, η_I) , the joint posterior is

$$\mu(\theta \mid s_D^*, s_I^*) = \frac{\pi^{\eta_D}(s_D^* \mid \theta) \pi^{\eta_I}(s_I^* \mid \theta) \mu_0(\theta)}{\sum_{\theta' \in \Theta} \pi^{\eta_D}(s_D^* \mid \theta') \pi^{\eta_I}(s_I^* \mid \theta') \mu_0(\theta')}.$$

2026 discordant calls (illustrative)

$(s_D^*, s_I^*) = (\text{RLA}, \text{RS})$, $(\eta_D, \eta_I) = (0.40, 0.30)$, uniform prior μ_0 ; likelihoods 0.090, 0.140, 0.030 give

$$\mu(\cdot \mid \text{RLA}, \text{RS}) \approx (0.35_{\text{RLA}}, 0.54_{\text{RS}}, 0.12_{\text{JN}}).$$

Discordance **splits** viability mass *within* Θ ; candidates outside Θ receive none.

Model: from utility to vote probabilities

Voter j has type (α_j, β_j, M_j) : expressive weight α_j , instrumental weight β_j , and match score $M_j(c) \in [0, 1]$, the expressive affinity with candidate c . Utility:

$$U_j(c, \theta) = \underbrace{\alpha_j M_j(c)}_{\text{expressive}} + \underbrace{\beta_j M_j(c) \mathbf{1}\{c \in \text{runoff}(\theta)\}}_{\text{instrumental}} + \varepsilon_{jc}, \quad \varepsilon_{jc} \sim \text{Gumbel (i.i.d.)}.$$

Perceived viability $q_c(\mu) \in [0, 1]$ is the probability the voter assigns to candidate c reaching the runoff: $q_c(\mu) = 1$ for Fujimori (her passage was confirmed), $q_c(\mu) = \mu(c)$ for $c \in \Theta$, and $q_c(\mu) = 0$ otherwise. Writing μ_j^s for voter j 's posterior after the signal profile s , the choice probability is logit:

$$\mathbb{P}_j(c \mid s) = \frac{\exp(M_j(c) [\alpha_j + \beta_j q_c(\mu_j^s)])}{\sum_{c'} \exp(M_j(c') [\alpha_j + \beta_j q_{c'}(\mu_j^s)])}.$$

The mechanism: viability–affinity interaction

Viability–affinity interaction

A rise in q_c pulls voter j toward c **in proportion to** $M_j(c)$: a viable but expressively rejected candidate ($M_j(c) \approx 0$) exerts no pull. Formally, $\partial \mathbb{P}_j(c | s) / \partial q_c \propto M_j(c) \geq 0$.

The flash is **public**: it raises q_c by the *same* amount for every voter in the location. But the response is not uniform — it is scaled by affinity, so only voters who already find c acceptable actually switch. Aggregating, the gain for c concentrates among voters **already sympathetic to** c , and the location-level effect τ_c is **scaled by the local affinity mass** on c . Same signal, different movement: this is the economic core of the results.

From individual choices to *acta*-level shares

Secret ballot: ONPE records only *acta*-level counts, so the logit is identified from shares. Let N_a be the valid votes in *acta* a and $V_{jc} = 1$ if voter j votes for c (else 0). The **observed vote share** for candidate c in *acta* a is

$$Y_{ac} = \frac{1}{N_a} \sum_{j \in a} V_{jc}, \quad \mathbb{E}[V_{jc} \mid \mu_j] = \mathbb{P}_j(c \mid \mu_j).$$

Baseline posterior $\mu_j^{(0)} = \mu_0$ (Sunday); post-flash $\mu_j^{(1)} = \mu_j(\cdot \mid s_D^*, s_I^*)$ (Monday). The **individual information effect** is

$$\delta_{jc} := \mathbb{P}_j(c \mid \mu_j^{(1)}) - \mathbb{P}_j(c \mid \mu_j^{(0)}), \quad \tau_{ac} = \frac{1}{N_a} \sum_{j \in a} \delta_{jc},$$

i.e. within an *acta* the effect is the average of the individual effects.

The estimand and its model counterpart

Averaging τ_{ac} over the treated population gives the **ATT estimand** for candidate c ; its model counterpart Δ_c is computable in closed form from the structural choice model:

$$\tau_c := \mathbb{E}[Y_{ac}(1) - Y_{ac}(0) \mid T_\ell = 1] = \underbrace{\mathbb{E}\left[\int \delta_{jc} dF_a(j) \mid T_\ell = 1\right]}_{=\Delta_c},$$

where F_a is the within-*acta* distribution of voter types (mass $1/N_a$ on each voter $j \in a$). The unobservable individual effect δ_{jc} reaches the data only through its *acta* average τ_{ac} .

Identification: assumptions

Let H_a be the vector of pre-treatment covariates (*acta* demographics and location structural variables) and $T_\ell \in \{0, 1\}$ the treatment indicator of location ℓ .

- **A1 (conditional independence)**. Given the state θ , the Datum and Ipsos flashes factor (used in Prop. 1) — independent samples and weighting; stress-tested next.
- **A2 (selection on observables + overlap)**. $Y_{ac}(0) \perp\!\!\!\perp T_\ell \mid H_a$ and $0 < \mathbb{P}(T_\ell=1 \mid H_a) < 1$ — justified because displacement followed the contractor's logistical protocol (routes, delivery times), correlated with district socioeconomics but *orthogonal to political preferences*.
- **A3 (SUTVA)**. An *acta*'s potential outcomes depend only on its own location's status — no between-location spillovers.

Identification: are the two polls independent?

A1 requires independence *conditional on* the true entrant θ . Datum and Ipsos draw separate samples with different field teams and weighting, so their sampling noise is independent; what they share is the *electorate* — which is the signal θ , exactly what A1 conditions out.

- The 2026 calls were **discordant** ($s_D^* \neq s_I^*$): identical methods would have produced the same call. Discordance is direct evidence the errors did not co-move.
- Their methods are similar but not identical, so some residual error correlation is plausible. That would make the two flashes carry *less* independent information, splitting viability mass *more* diffusely — which reinforces, not reverses, the sign predictions. A robustness check allows a correlation parameter ρ in the joint kernel.

Identification: what we cannot measure

Treatment is a bundle

The flash does not arrive alone: Monday voters also saw live media coverage, news commentary, and the ONPE partial-count platform. We identify the effect of the Monday *information environment* as a whole, not the flash in isolation.

- These channels are neither separately observed nor separable, so the estimand is the joint effect of the post-flash environment — the honest object the design delivers.
- This does not threaten identification (A2 still holds: displacement was logistical, not political), but it bounds interpretation: “flash estimates” is shorthand for the overnight information shock they anchored.

Identification: the central result

Proposition 2 (Identification of τ_c)

Under A2–A3, with control regression $m_0(h) := \mathbb{E}[Y_{ac} \mid H_a = h, T_\ell = 0]$ (the average control share at covariate profile h),

$$\tau_c = \underbrace{\mathbb{E}[Y_{ac} \mid T_\ell = 1] - \mathbb{E}[m_0(H_a) \mid T_\ell = 1]}_{\text{observable: the matching estimand}} = \underbrace{\Delta_c}_{\text{structural}} .$$

Two edges close the triangle:

- **(I) structural identity** $\tau_c = \Delta_c$ — definitional, from how the model maps beliefs to shares; it lets the measured ATT be read as the behavioral value of the added information.
- **(II) population identification** — selection-on-observables identifies the treated counterfactual $\mathbb{E}[Y_{ac}(0) \mid T_\ell = 1]$ from matched controls.

Treatment as a change of experiment: theory \leftrightarrow data

A *Sunday* voter decides under the **null experiment** π^\emptyset (no flash, posterior = μ_0); a *Monday* voter under the **flash experiment** $\pi^F = \pi^{\eta_D} \otimes \pi^{\eta_I}$ (posterior $\mu^{(1)}$). The null garbles every experiment, so $\pi^F \succeq_B \pi^\emptyset$ — strict once $\eta_D, \eta_I < 1 - 1/K$. Treatment is a **Blackwell improvement**, and τ_c is its behavioral value:

$$\underbrace{\pi^F \succeq_B \pi^\emptyset}_{\text{information design}} \Rightarrow \underbrace{\delta_{jc} = \mathbb{P}_j(c | \mu_j^{(1)}) - \mathbb{P}_j(c | \mu_j^{(0)})}_{\text{updating / choice}}$$
$$\Rightarrow \underbrace{\tau_c = \mathbb{E}[\int \delta_{jc} dF_a | T_\ell = 1]}_{\text{structural estimand}} = \Delta_c = \underbrace{\mathbb{E}[Y_{ac} | T_\ell = 1] - \mathbb{E}[m_0(H_a) | T_\ell = 1]}_{\text{matching estimator}}.$$

What the theory fixes, what the data delivers

Blackwell fixes the *value* of the extra information, not its *direction*: which c gains comes from the updating arrow, scaled by $M_j(c)$. National viability (experiment level) can diverge from local gain (updating level) — the Sánchez case.

Hypotheses (for the treated Lima Sur sample)

Within the right-leaning Lima sample, viable gains rank by **match**, not viability alone: Nieto (off-axis, “clean”) > López Aliaga (right-aligned, tied to the congressional pact) > Sánchez (left-anchored, provincial base).

H1. Nieto gains the most: $\tau_{JN} > 0$, largest among viable.

H2. López Aliaga intermediate: $0 < \tau_{RLA} < \tau_{JN}$, $\tau_{RLA} \geq \tau_{RS}$.

H3. Sánchez gains least among viable, despite national viability.

H4. Fujimori unmoved ($\tau_{KF} \approx 0$, at most weakly positive): her entry is confirmed in every state.

H5. Non-viable candidates lose: $\tau_c \leq 0$ (clearest: Álvarez, López Chau; Belmont also declines).

Adding-up: $\sum_c Y_{ac} = 1 \Rightarrow \sum_c \tau_c = 0$.

Data

Sample: Lima Sur — 354 voting locations, 4930 *actas*; 13 treated, 341 control pool.

INEI (Redatam census)

- Georeferenced at the block (*manzana*) level.
- Population, migration, language, education, health insurance, services, housing.

ONPE

- *Acta*-level results, 2021 and 2026 general elections.
- 2026 electoral roll: demographic composition of registered voters.

Linkage. For each location ℓ , a 1 km buffer; census blocks $B(\ell)$ within it aggregated by population weights (pop $_b$, v_b the value at block b):

$$V_\ell = \frac{\sum_{b \in B(\ell)} \text{pop}_b v_b}{\sum_{b \in B(\ell)} \text{pop}_b}.$$

Consistent with *Elige tu local*: voters select polling places near their residence.

Cardinality matching: the balance program

With only **13 treated clusters**, propensity-score models are unstable. Cardinality matching instead fixes the balance target *ex ante* and maximizes the retained control sample subject to it.

Let \mathcal{C}_0 be the control pool, $q_\ell \in \{0, 1\}$ the selection indicator, n_ℓ the *actas* at location ℓ , and $\mathcal{C}^* = \{\ell : q_\ell = 1\}$:

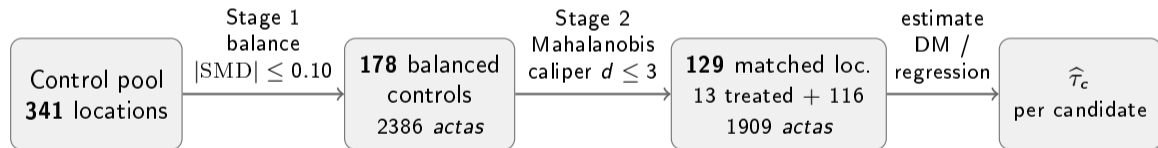
$$\max_{\{q_\ell\}} \sum_{\ell \in \mathcal{C}_0} q_\ell n_\ell \quad \text{s.t.} \quad |\text{SMD}_j| \leq \delta_j, \quad j = 1, \dots, J, \quad \text{SMD}_j = \frac{\bar{H}_{j,T} - \bar{H}_{j,\mathcal{C}^*}}{s_j},$$

where $\bar{H}_{j,T}$, $\bar{H}_{j,\mathcal{C}^*}$ are treated and matched-control means of covariate j and s_j its pooled SD.

- Strict per-covariate rule: $\delta_j = 0.10$ for all $J = 9$ covariates, no exceptions; fine balance on the district marginal. Solved as an integer program in Python.

Cardinality matching: the estimation pipeline

Stage 2 (grouping). For each treated location we rank controls by **Mahalanobis distance** $d(l, l') = \sqrt{(x_l - x_{l'})^\top \Sigma^{-1} (x_l - x_{l'})}$ — covariate distance rescaled by Σ so correlated covariates are not double-counted — keep the nearest, and drop any with $d > 3$ (the caliper). Group sizes range 3–10.



Matching is at the *location* level; outcomes are estimated at the *acta* level.

The procedure, step by step

From raw data to $\hat{\tau}_c$

- 1 **Covariates.** For each location ℓ build H_ℓ : census variables (1 km *manzana* buffer) plus 2021 vote shares — nine covariates in all.
- 2 **Stage 1 (balance).** Solve the integer program: pick the controls that *maximize retained actas* subject to $|SMD_j| \leq 0.10$ for every covariate. This fixes balance *before* looking at outcomes. \Rightarrow 178 controls.
- 3 **Stage 2 (grouping).** For each treated location, rank the selected controls by Mahalanobis distance, keep the nearest, and drop any with $d > 3$. \Rightarrow 13 groups, 116 controls (129 locations).
- 4 **Estimate.** Within each group take the treated–control *acta*-mean gap; average across groups with *acta* weights $\Rightarrow \hat{\tau}_c^{DM}$. A group-fixed-effects regression gives $\hat{\tau}_c^R$ as a check.
- 5 **Inference.** Leave-one-treated-location-out and within-group permutation tests, given only 13 treated clusters.

Two estimators on the matched sample

1. **Acta-weighted difference in means (DM).** Within group i , contrast treated and control *acta* means $\hat{\Delta}_{i,c} = \bar{Y}_{i,c}^T - \bar{Y}_{i,c}^C$; weight by the treated *acta* share $w_i = n_i/N_T$ (n_i treated *actas* in group i , $N_T = \sum_i n_i$):

$$\hat{\tau}_c^{\text{DM}} = \sum_{i=1}^{13} w_i \hat{\Delta}_{i,c}, \quad \sum_i w_i = 1.$$

2. **Regression-adjusted ATT.** Pooled OLS over *actas* a , with treatment indicator $T_a \equiv T_{\ell(a)}$, group fixed effects γ_i , and *acta*-level demographic controls X_a :

$$Y_{a,c} = \tau_c T_a + \gamma_{i(a)} + X_a^\top \lambda_c + u_{a,c}, \quad \text{cluster-robust SE at the location level.}$$

Inference caveat: 13 treated clusters is a known limitation; within-group permutation tests under the sharp null are the preferred inferential base.

Covariate balance

Covariate	Treated mean	Control (all)	Control (matched)	SMD before	SMD after
Socioeconomic stratum	2.207	2.599	2.179	-0.629	0.045
Indigenous-language share	0.110	0.091	0.112	0.473	-0.028
Higher-education share	0.249	0.312	0.254	-0.733	-0.064
Internet-access share	0.361	0.453	0.372	-0.786	-0.100
2021 left vote share	0.254	0.247	0.257	0.201	-0.095
2021 right vote share	0.279	0.301	0.279	-0.347	0.013
2021 Fujimori vote share	0.169	0.163	0.173	0.167	-0.099
Female-voter share	0.492	0.499	0.495	-0.205	-0.098
Voter age (group index)	2.755	2.855	2.772	-0.193	-0.032

Largest |SMD| falls from 0.79 to 0.100; every covariate clears the $\delta_j = 0.10$ tolerance.

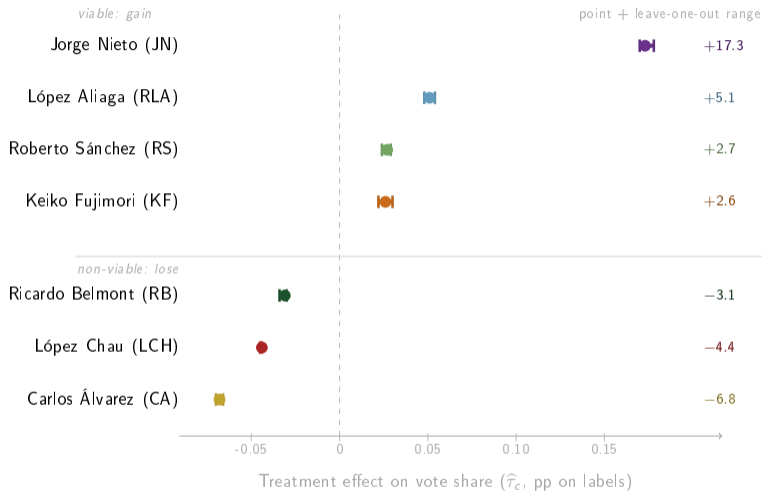
Main results: treatment effects on vote shares

Candidate	$\hat{\tau}_c^{\text{DM}}$	$\hat{\tau}_c^{\text{R}}$
Keiko Fujimori (KF)	0.026*** (0.007)	0.026*** (0.004)
Roberto Sánchez (RS)	0.027*** (0.006)	0.027*** (0.003)
Rafael López Aliaga (RLA)	0.051*** (0.007)	0.051*** (0.004)
Jorge Nieto (JN)	0.173*** (0.008)	0.173*** (0.004)
Ricardo Belmont (RB)	-0.031*** (0.004)	-0.031*** (0.003)
Carlos Álvarez (CA)	-0.068*** (0.003)	-0.068*** (0.002)
Alfonso López Chau (LCH)	-0.044*** (0.001)	-0.044*** (0.001)

Share units; cluster-robust SEs at the location level. $N = 1909$ *actas*; 129 matched locations. *** $p < 0.01$.

DM and regression-adjusted estimators agree in sign and magnitude for every candidate: the global balance carries the identification.

The effect at a glance



Acta-weighted ATT; caps span the thirteen leave-one-treated-location-out reruns. $N = 1909$ *actas*, 129 matched locations.

Reading the magnitudes

- 1 **Viable gain, non-viable lose** — exactly the sign pattern of H1–H3, H5.
- 2 **Fujimori**: small but significant +2.6 pp — weak reinforcement (H4).
- 3 **Reallocation concentrated on Nieto**: +17.3 pp, three to seven times any other gain.

Within-viable ordering: Nieto > López Aliaga > Sánchez

Tracks **affinity, not national viability**. Nieto (off-axis “clean” option, highest match) takes the bulk; López Aliaga’s match is cut by his tie to the congressional pact (+5.1); Sánchez — the eventual runoff entrant — is expressively most distant in this right-leaning sample and gains least (+2.7).

The seven leading effects sum to +0.134: the displaced share is drawn from the long tail of minor candidates (adding-up, H5).

- **Location-weighted estimand.** Equal weight per treated location: signs and significance unchanged (Nieto +0.176, López Aliaga +0.054, Sánchez +0.025).
- **Leave-one-treated-location-out.** Thirteen reruns: no sign reversal, no loss of significance at 5%; Nieto stays within [0.170, 0.178]; each viable candidate's contrast positive in ≥ 11 of 13 groups.
- **Balance tolerance.** Re-solving at $\delta \in \{0.05, 0.10, 0.15\}$ moves estimates negligibly; all remain significant at 1%.

Conclusion

- A late **viability signal** causally reallocates votes — every effect significant at 1% and robust to leave-one-out, weighting, and tolerance checks.
- The reallocation runs through the **local distribution of expressive affinities**, not the signal alone: q_c moves uniformly, but the vote it moves is scaled by $M_j(c)$.
- A candidate can advance nationally on a signal yet move few local votes: **viability travels with the signal; its reallocation is governed by local affinity** (the Sánchez case).
- First-order relevance for Peru: institutional instability, fragmentation, and political volatility make voters unusually responsive to viability signals.

Caveats and work in progress

This is a rushed first pass

The election was **barely two months ago** (April 2026); the georeferenced census and *acta*-level files arrived late, leaving little time before this draft. The findings are stable but the inference layer is still being finalized.

- **Rosenbaum sensitivity (1:k)**. The current sign-flip enumeration is valid only for 1:1 pairs. The correct version uses per-location scores, a worst-case within-set tilt under Γ , and exact combination across the 13 independent groups (k varies 3–10).
- **Heterogeneity**. Effects by a Right–Left index (interaction terms) — not yet in the results files.
- **Few-cluster inference**. Wild cluster bootstrap / randomization inference to complement cluster-robust SEs with only 13 treated clusters.

Thank you

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